









Advanced SiPM camera trigger with Convolutional Neural Networks

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• Future camera for the LSTs, using 7987 SiPMs pixels instead of 1855 PMTs.









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 Currently working on the trigger level, on r0 data. Receiving data at ~1 GHz, so one sample of 7987 pixels per ns. We are working on the trigger of disited working. Detect production







Trigger at the CTP



- PIXELS ARE HEXAGONAL, normally to apply DL algorithms we first map the hexagonal grid to square pixels.
- But time is crucial at the CTP, so:



• Multiple options: NSB/shower, NSB/proton/gamma, or proton/gamma separation.



Pulsar analysis



- Rapidly rotating neutron stars, that emit regular pulses with rotational periods that can go up to the ms.
- History of the Dragonfly proposals ...











THANKS, QUESTIONS?



Trigger at the CTP



• Multiple trigger levels are expected.



• Faint events that were discarded at the trigger level can be taken into consideration, reducing the threshold and the sensitivity at low energies.



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