



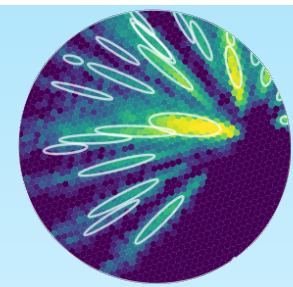
Development Status

Design, what we have, and where we are going

Current Code Base



based on Scientific Python Stack (NumPy/SciPy/AstroPy/PyTables/Numba)



ctapipe

standard analysis tools

ctapipe-process
ctapipe-apply-model
ctapipe-train
ctapipe-fileinfo
...

framework

Data Input
Event model
Instrument Model
HDF5 Data IO
Configuration
Logging
Provenance

algorithms

calibration
image processing
reconstruction
atmosphere

pyIRF

Cut Optimization

Gamma-hadron
Theta²

IRFs

Aeff
PSF
Edisp

Performance

Metrics

sensitivity
angular resolution
energy resolution

neobench

benchmarking of sim

processing

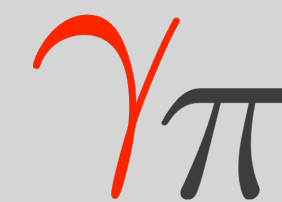
Performance checks

pyeventio

low-level simulation
data access

zfitsreader

low-level DL0/Event
data input (from ACADA)



A Python package for
gamma-ray astronomy

IRF Format and output

Covers most but not all functionality...

Division of Responsibilities



! :
some structural re-organization
could help (topic for later
discussion)

DPPS-Common

- ▶ ctapipe.io (HDF5),
ctapipe.core,
ctapipe.containers,
ctapipe.instrument,
ctapipe.utils,
ctapipe.visualization
- ▶ zfitsreader
(with ACADA)

DPPS-DataPipe

- ▶ ctapipe.reco,
ctapipe.image!,
ctapipe.atmosphere
- ▶ parts of ctapipe.calib
(with CalibPipe !)
- ▶ pyirf
- ▶ benchmark tools
- ▶ DataPipe Workflows
(with WMS)

DPPS-SimPipe

- ▶ ctapipe.io.
SimTelEventSource!
 - ▶ pyeventio ?
- SUSS:**
- ▶ gammapy

Standards:

- ▶ CTA Software Programming Standards Document
- ▶ Developer Guides
 - CTAO Developer Guidelines (work in progress, but useful for python already)
 - ctape developer documentation on readthedocs

Practices:

- ▶ GitLab vs GitHub:
 - Github only for existing packages shared outside of DataPipe
- ▶ New Software Projects
 - Templates for python packages available in Computing GitLab space
- ▶ Quality Gates
 - CTAO SonarQube instance

Common core functionality



What we have now
covers most of core
functions

But not in full detail
(missing things inside)

ctapipe-process

ctapipe-process

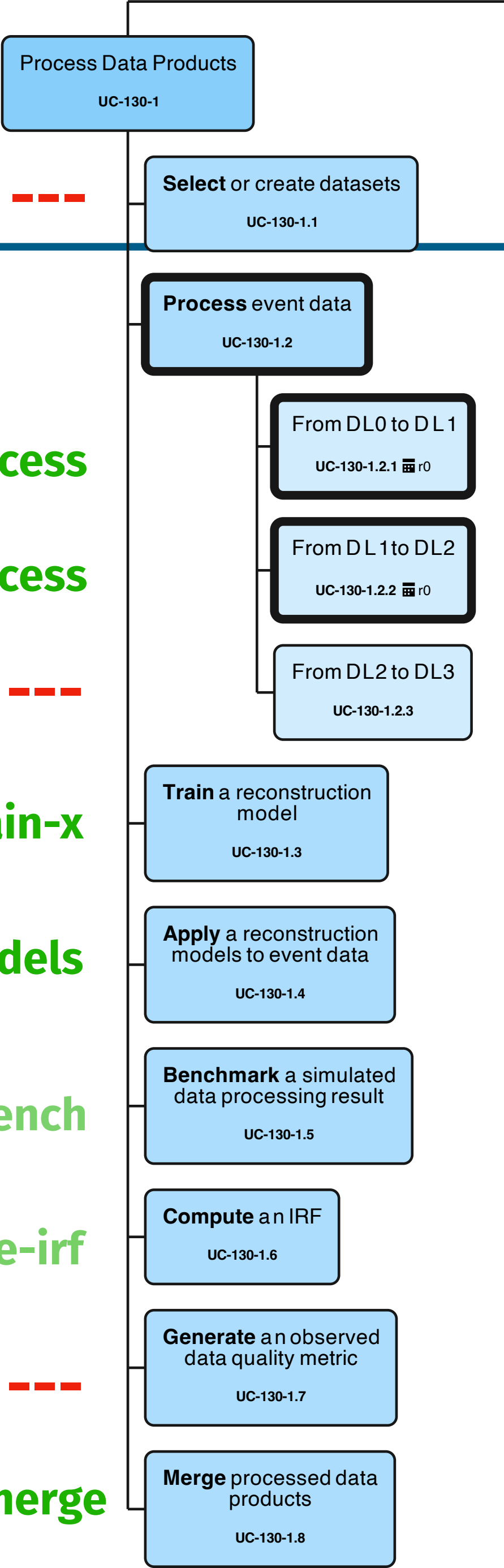
ctapipe-train-x

ctapipe-apply-models

neobench

ctapipe-make-irf

ctapipe-merge



Higher-Level Functionality



ctapipe-train-energy-regressor

ctapipe-train-particle-classifier

ctapipe-train-disp-reconstructor

neobench

Produce Reconstruction Models
UC-130-2.1

Produce Energy Model
UC-130-2.1.1

Produce Gammaness Model
UC-130-2.1.2

Produce Mono Geometry Disp Model
UC-130-2.1.3

Produce Event Type Model(s)
UC-130-2.1.4

Benchmark (Verify) Results
UC-130-2.2

Benchmark DL0 event data
UC-130-2.2.1

Benchmark DL1 event data

Produce DL3 Data Products for an observation
UC-130-3.1

Process events from DL0 to DL3
UC-130-3.1.1

Marginalize general IRFs to the observation
UC-130-3.2.2

Compute IRFs tailored to observation
UC-130-3.2.3

Produce DataPipe Quality Metrics
UC-130-3.2

Generate DL0 quality metrics
UC-130-3.2.1

Generate DL1 quality metrics
UC-130-3.2.2

ctapipe-process
ctapipe.io.ZFITSDataSource

R0 from Simulations:

- ▶ EventIO format
- ▶ Transformed into DL0 by SimTelEventSource

DL0 from Observation (ACADA):

- ▶ ZFITS format documented in R1/DL0 data models and ACADA-DPPS ICD

(R0, R1) DL1, DL2 used in pipeline:

- ▶ HDF5 format, Data Model specified in ctapipe.containers
- ▶ I/O implemented in:
 - HDF5EventSource/DataWriter (event-wise)
 - HDF5Merger/TableLoader (column-wise)

DL3 Event + IRF + Monitoring:

- ▶ FITS format (to be implemented)...

Category-B:

- ▶ Runs on-site data centers (unless data have already transferred)
- ▶ Starts at end of data taking, should be **finished by mid-next day**
- ▶ ≈ 20 observations per night

Category-C:

- ▶ Runs at off-site data centers
- ▶ Up to a **month to finish**
- ▶ can wait for sims, for example, or do fancier algorithms

Same software and workflows*,
differ only by configuration for
"quick and dirty" to "advanced
final analysis"

*However, may skip some workflows steps if needed

Missing Pieces



Known Missing Functionality



Event Types

- ▶ Classify events into bins of *reconstruction* and *background* quality
- ▶ machine-learning step to predict the reconstruction uncertainties?

DL2→ DL3 conversion!

- ▶ Choose best reconstruction
- ▶ Categorize by Event Type
- ▶ Write FITS output in proper format

Simulating Calibration:

- ▶ R1 Calibration not fully simulated (no pedestal variances, etc)

DL1 Calibration for Observations (and simulations)

- ▶ R1 calibration happens in the EventSource (telescope responsibility)
- ▶ (re-)Calibration or refinement in the DL0→DL1 step doesn't exist

To be expanded
during this
workshop!

Observation processing:

- ▶ NSB-safe Image cleaning (using pedestal variances, times) → partially there, but see above
- ▶ Reading and Application of pointing corrections (translations and rotations)

Details of Cat-B/Cat-C

- ▶ alternate scenarios of top-level UC (not yet written)

Generation of SAG IRFs

- ▶ Uses potentially different reconstruction and calibration code...
- ▶ We need to develop a workflow for this

Potentially Missing Use Cases



To be expanded
during this
workshop!

Config Management:

- ▶ We will have many config files for different stages and types of processing
- ▶ How to manage and track them?
- ▶ Do we need a configuration UI?

Workflow Management

- ▶ Workload provides a lot of functionality for monitoring workflows.
- ▶ Is it enough?
- ▶ Do we need our own databases?

Suggest a change to function tree or use cases:

- ▶ open issue or merge-request on [dpps-use-cases](#) repo

Ask a question or Suggest a task for DataPipe group:

- ▶ Quick: use the [#dpps-datapipe](#) Slack channel
- ▶ Advanced/Tracked: